



Motivation

- Large-scale antenna arrays are widely deployed in radar, sonar, wireless communication, and sensing applications
- Classical MVDR beamforming scales $O(M^3)$ due to covariance inversion
- Real-time implementation** of MVDR beamforming in large arrays becomes computationally **infeasible**

Background

- Consider an array of M antennas receiving a desired signal and L interferers.
- The received signal at time t :

$$\mathbf{x}_t = \mathbf{a}(\theta_0)s_0(t) + \sum_{l=1}^L \mathbf{a}(\theta_l)s_l(t) + \mathbf{s}_n(t)$$

- The beamformer output:

$$\mathbf{y}_t = \mathbf{w}^H \mathbf{x}_t$$

- The solution to MVDR Beamformer:

$$\mathbf{w} = \frac{R^{-1} \mathbf{a}(\theta_0)}{\mathbf{a}(\theta_0)^H R^{-1} \mathbf{a}(\theta_0)}$$

- Practically, R is not known and needs to be estimated using received signal. R at time step n with m snapshots:

$$R_n = \frac{1}{m} \sum_{i=n-m+1}^n \mathbf{x}_i \mathbf{x}_i^H$$

Proposed Method

- Recursive update rule for R :

$$R_{n+1} = \alpha R_n + (1 - \alpha) \mathbf{x}_n \mathbf{x}_n^H \quad (0 < \alpha < 1)$$

- Update for R^{-1} using Sherman-Morrison formula:

$$R_{n+1}^{-1} = \frac{R_n^{-1}}{\alpha} - \frac{(1 - \alpha)}{\alpha} \frac{R_n^{-1} \mathbf{x}_n \mathbf{x}_n^H R_n^{-1}}{\alpha + (1 - \alpha) \mathbf{x}_n^H R_n^{-1} \mathbf{x}_n}$$

- Low rank SVD approximation:

$$R_{n+1}^{-1} \approx U_K D_{K,n+1}^{-1} U_K^H \quad (K \ll M)$$

- Initialization: One-time low-rank SVD $O(M^3)$, thereafter, linear-scaling updates $O(MK^2)$

Algorithm

Inputs: Initial covariance matrix R_n , data vectors $\mathbf{x}_n, \dots, \mathbf{x}_N$, forgetting factor α , low-rank dimension K

- Initialize: $R \leftarrow R_n$
- Compute low-rank SVD: $R \approx U_K D_K U_K^H$
- For each time step $i = n \dots N$:
- $\mathbf{x} \leftarrow \mathbf{x}_n$
- Update the inverse submatrix:

$$D_{K,n+1}^{-1} = \frac{D_{K,n}^{-1}}{\alpha} - \frac{(1 - \alpha)}{\alpha} \frac{D_{K,n}^{-1} U_K^H \mathbf{x}_n \mathbf{x}_n^H U_K D_{K,n}^{-1}}{\alpha + (1 - \alpha) \mathbf{x}_n^H U_K D_{K,n}^{-1} U_K^H \mathbf{x}_n}$$

- Compute the Beamforming weights:

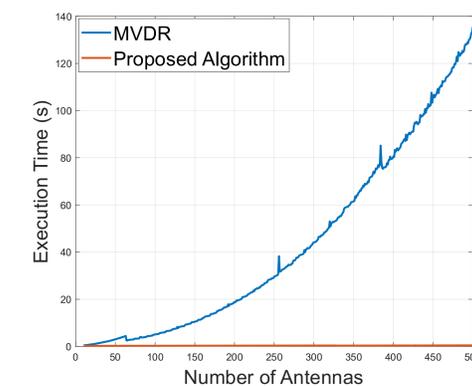
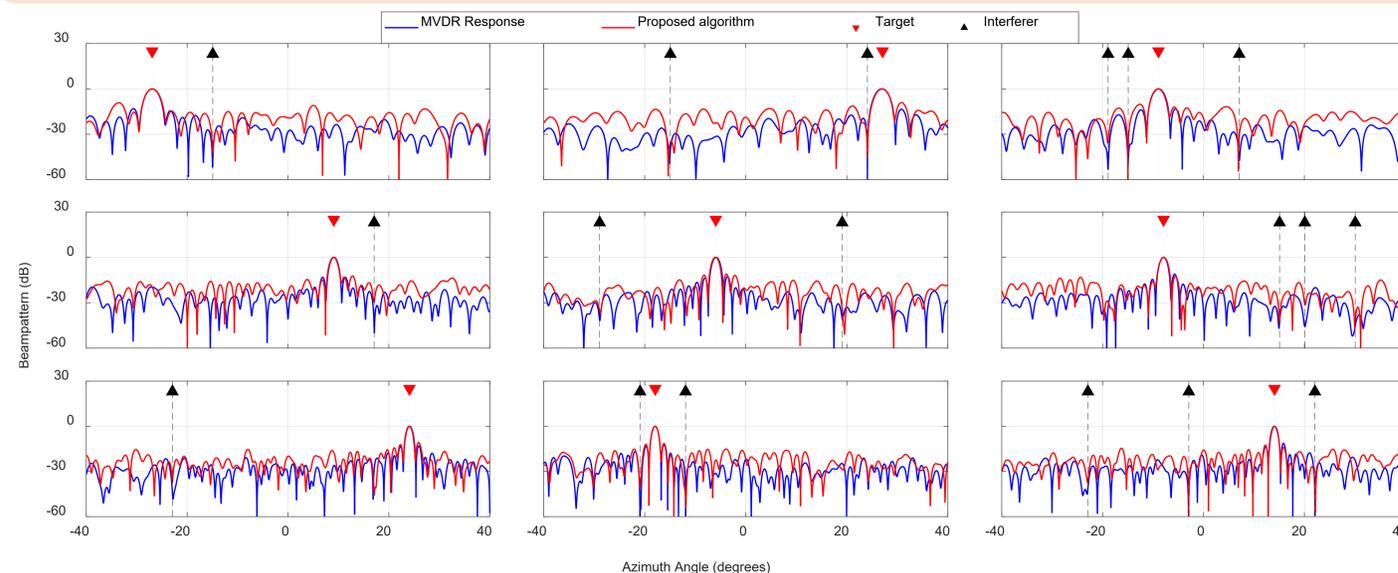
$$\mathbf{w} = \frac{U_K D_{K,n+1}^{-1} U_K^H \mathbf{a}(\theta_0)}{\mathbf{a}(\theta_0)^H U_K D_{K,n+1}^{-1} U_K^H \mathbf{a}(\theta_0)}$$

Output: Updated beamforming weights \mathbf{w}

Results

M	L	Main Lobe Width ($^\circ$) \downarrow		Null depth (dB) \downarrow		Side Lobe Level (dB) \downarrow	
		MVDR	Proposed	MVDR	Proposed	MVDR	Proposed
50	1	2.27	2.32	-49.56	-42.44	-13.02	-9.14
50	2	2.38	2.31	-51.31	-40.10	-13.48	-9.06
50	3	2.09	2.03	-49.55	-35.29	-13.19	-10.20
75	1	1.37	1.37	-47.54	-29.32	-13.12	-12.32
75	2	1.36	1.33	-41.02	-34.84	-12.75	-11.05
75	3	1.34	1.41	-44.70	-39.53	-11.11	-12.55
100	1	1.10	1.08	-44.01	-37.13	-13.05	-10.76
100	2	1.07	1.07	-55.54	-44.56	-12.27	-11.47
100	3	1.06	1.08	-45.83	-41.78	-11.37	-12.47

Results



MVDR: $O(M^3)$
Proposed: $O(MK^2)$

Limitations

- When the signal is above the noise floor, the proposed method fails to place nulls as accurately as conventional MVDR
- The SINR gain gradually declines over time, but can be restored through periodic reinitialization

